

# Determinantal point process models and statistical inference

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- 1 Introduction
- 2 Definition, existence and basic properties
- 3 Parametric stationary models
- 4 Approximation of the eigen expansion
- 5 Inference : methodology
- 6 Conclusion and references

In short

- DPPs are general models for random processes with **negative dependencies**.
- Their general definition has been introduced by O. Macchi in 1975 to model fermions (i.e. particles in repulsion)
- DPPs arise in many examples of Probability theory (much before 1975)
- They have been used for statistical purposes more recently (for about 5 years).

## Example 1: the "descent subsequence"

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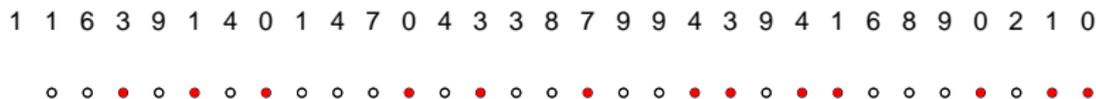




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○ ○ ● ○ ● ○ ● ○ ○ ○ ● ○ ● ○ ○ ● ○ ○ ● ● ○ ● ● ○ ○ ○ ● ○ ● ●

This is a DPP!

With  $N = 100$ .

From the "descent subsequence"



From an independent sampling



## Example 2: the Ginibre DPP

Let  $M$  be an  $n \times n$  matrix with iid complex Gaussian entries.  
Then the  $n$  eigenvalues of  $M$  are

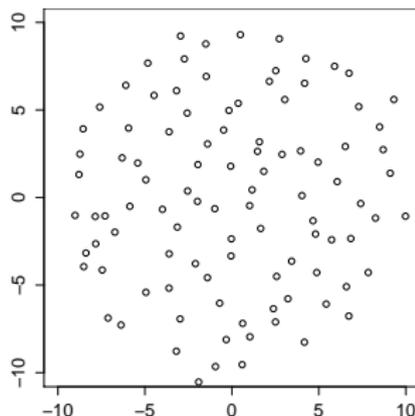
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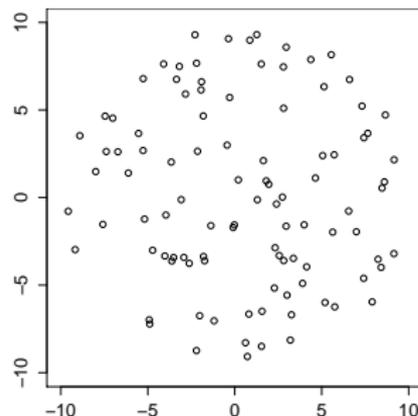
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Left : Ginibre DPP ( $n = 100$ ).

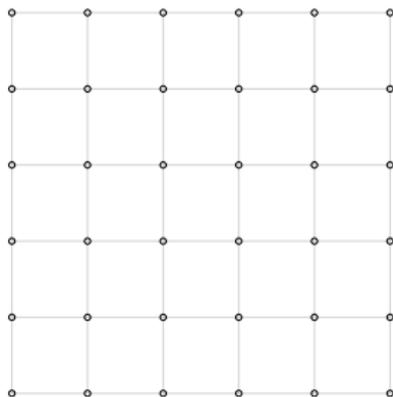


Right : 100 iid points in the disk.



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Aim : sample edges (with negative dependence) from a graph



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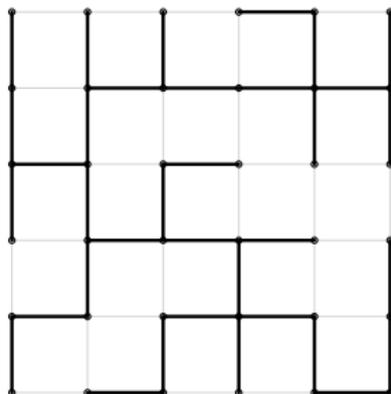
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Random spanning tree

"tree" = any 2 vertices are connected by exactly one path

"spanning" = all vertices are connected

"random" = uniform over all possible spanning trees



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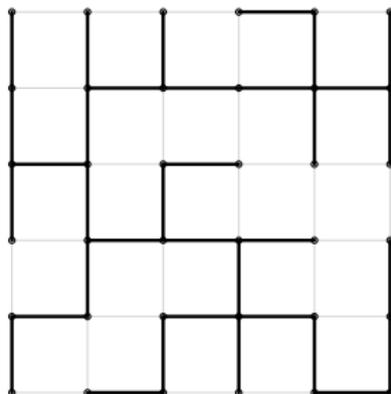
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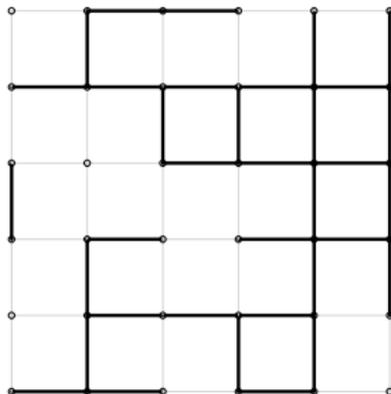
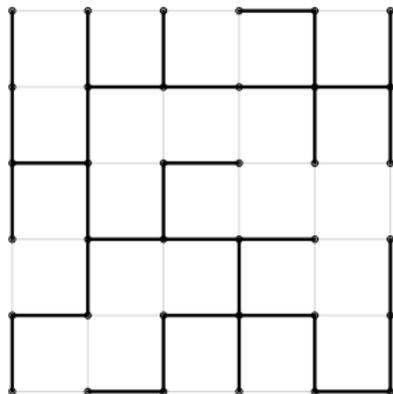
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The repartition of the edges on the graph is a DPP!

Left: spanning tree.

Right: independent sampling of the edges



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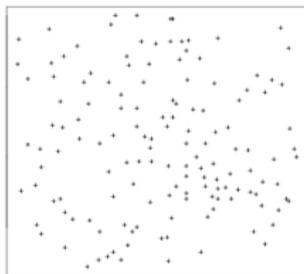
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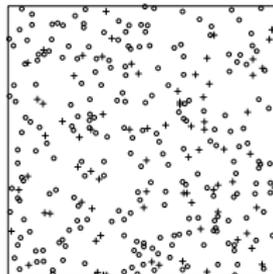
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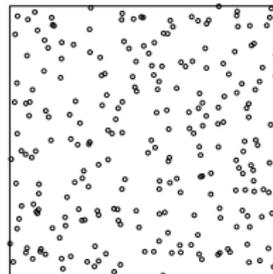
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- In Machine Learning : for instance, by imposing diversity (through a prior with negative dependencies) in the categories of an unsupervised classification problem.
- In surveys or random designs : negative dependencies in the sampling may reduce the variance of an estimate (ex : Monte Carlo approximation of the integral of a smooth function)
- Some real-data naturally involve negative dependencies:



Cellular Network



Kidney cells (hamster)



Oak and Beech trees

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In general:

- moments are not expressible in closed form;
- likelihoods involve intractable normalizing constants;
- elaborate MCMC methods are needed for simulations and approximate likelihood inference;
- for infinite Gibbs point processes defined on  $\mathbb{R}^d$ , ‘things’ become rather complicated (existence and uniqueness)

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- (d) the DPP on any compact set can easily be simulated;
- (e) parametric models are available, and inference can be done by MLEs or using the moments.

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Interpretation: for  $i, j \in \{1, \dots, N\}$ ,

$$K_{ii} = P(i \in X)$$

$K_{ij} \approx$  measure of similarity between  $i$  and  $j$ . If  $K$  is symmetric

$$P(i, j \in X) = \begin{vmatrix} K_{ii} & K_{ij} \\ K_{ji} & K_{jj} \end{vmatrix} = P(i \in X)P(j \in X) - K_{ij}^2$$

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- For any borel set  $B \subseteq \mathbb{R}^d$ ,  $X_B = X \cap B$ .
- For  $n > 0$ ,  $\rho^{(n)}$  is the  $n$ 'th *order product density function* of  $X$ .  
Intuitively,

$$\rho^{(n)}(x_1, \dots, x_n) dx_1 \cdots dx_n$$

is the probability that for each  $i = 1, \dots, n$ ,

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In particular  $\rho = \rho^{(1)}$  is the *intensity function*.

# Definition of a DPP on $\mathbb{R}^d$

Let  $C$  be a function from  $\mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{C}$ .

Denote  $[C](x_1, \dots, x_n)$  the  $n \times n$  matrix with entries  $C(x_i, x_j)$ .

$$\text{Ex : } [C](x_1) = C(x_1, x_1) \quad [C](x_1, x_2) = \begin{pmatrix} C(x_1, x_1) & C(x_1, x_2) \\ C(x_2, x_1) & C(x_2, x_2) \end{pmatrix}.$$

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Basic example : The Poisson point process with intensity  $\rho(x)$  is the special case where  $C(x, x) = \rho(x)$  and  $C(x, y) = 0$  if  $x \neq y$ .

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- If  $X \sim DPP(C)$ , then  $X_B \sim DPP(C_B)$
- Any smooth transformation or independent thinning of a DPP is still a DPP with explicit given kernel.
- Given a kernel  $C$ , there exists at most one  $DPP(C)$ .

# Existence

$C$  must be non-negative definite. Henceforth assume

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$$C_S(x, y) = \sum_{k=1}^{\infty} \lambda_k^S \phi_k^S(x) \overline{\phi_k^S(y)}, \quad (x, y) \in S \times S,$$

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**Theorem (Macchi, 1975)**

*Under (C1), existence of DPP( $C$ ) is equivalent to :*

$$\lambda_k^S \leq 1 \text{ for all compact } S \subset \mathbb{R}^d \text{ and all } k.$$

# Density on a compact set $S$

Let  $X \sim \text{DPP}(C)$  and  $S \subset \mathbb{R}^d$  be any compact set.

Recall that  $C_S(x, y) = \sum_{k=1}^{\infty} \lambda_k^S \phi_k^S(x) \overline{\phi_k^S(y)}$ .

## Theorem (Macchi (1975))

If  $\lambda_k^S < 1 \forall k$ , then  $X_S \ll \text{Poisson}(S, 1)$ , with density

$$f(\{x_1, \dots, x_n\}) = \exp(|S| - D) \det[\tilde{C}](x_1, \dots, x_n),$$

where  $D = -\sum_{k=1}^{\infty} \log(1 - \lambda_k^S)$  and  $\tilde{C} : S \times S \rightarrow \mathbb{C}$  is given by

$$\tilde{C}(x, y) = \sum_{k=1}^{\infty} \frac{\lambda_k^S}{1 - \lambda_k^S} \phi_k^S(x) \overline{\phi_k^S(y)}$$

# Simulation

Let  $X \sim \text{DPP}(C)$ .

We want to simulate  $X_S$  for  $S \subset \mathbb{R}^d$  compact.

Recall that  $X_S \sim \text{DPP}(C_S)$  with  $C_S(x, y) = \sum_{k=1}^{\infty} \lambda_k^S \phi_k^S(x) \overline{\phi_k^S(y)}$ .

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## Theorem (Hough et al. (2006))

For  $k \in \mathbb{N}$ , let  $B_k$  be independent Bernoulli r.v. with mean  $\lambda_k^S$ .  
Define

$$K(x, y) = \sum_{k=1}^{\infty} B_k \phi_k^S(x) \overline{\phi_k^S(y)}, \quad (x, y) \in S \times S.$$

Then  $\text{DPP}(C_S) \stackrel{d}{=} \text{DPP}(K)$ .

So simulating  $X_S$  is equivalent to simulate DPP( $K$ ) with

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- 2 Given  $M = m$ , generate  $B_1, \dots, B_{m-1}$

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- 3 simulate DPP( $K$ ) given  $B_1, \dots, B_M$  and  $M = m$ .  
The kernel  $K$  becomes w.l.o.g.

$$K(x, y) = \sum_{k=1}^n \phi_k^S(x) \overline{\phi_k^S(y)}$$

and DPP( $K$ ) is a *determinantal projection process*.

Simulation of a determinantal projection process:

$$K(x, y) = \sum_{k=1}^n \phi_k^S(x) \overline{\phi_k^S(y)} = \mathbf{v}(y)^* \mathbf{v}(x), \quad \mathbf{v}(x) = (\phi_1^S(x), \dots, \phi_n^S(x))^T.$$

DPP( $K$ ) has a.s.  $n$  points  $(X_1, \dots, X_n)$  that can be generated by the following Gram-Schmidt procedure

**sample**  $X_n$  from the density  $p_n(x) = \|\mathbf{v}(x)\|^2/n$ ;

**set**  $\mathbf{e}_1 = \mathbf{v}(X_n)/\|\mathbf{v}(X_n)\|$ ;

**for**  $i = (n - 1)$  to 1 **do**

**sample**  $X_i$  from the density (given  $X_{i+1}, \dots, X_n$ ) :

$$p_i(x) = \frac{1}{i} \left[ \|\mathbf{v}(x)\|^2 - \sum_{j=1}^{n-i} |\mathbf{e}_j^* \mathbf{v}(x)|^2 \right], \quad x \in S$$

**set**  $\mathbf{w}_i = \mathbf{v}(X_i) - \sum_{j=1}^{n-i} (\mathbf{e}_j^* \mathbf{v}(X_i)) \mathbf{e}_j$ ,  $\mathbf{e}_{n-i+1} = \mathbf{w}_i/\|\mathbf{w}_i\|$

# Summary

Therefore, given a kernel  $C$  :

- condition for existence of  $\text{DPP}(C)$  are known\*
- all moments of  $\text{DPP}(C)$  are explicitly known
- the density of  $\text{DPP}(C)$  on any compact set is known\*
- $\text{DPP}(C)$  can be easily and quickly simulated on any compact set\*

\* if the spectral representation of  $C_S$  is known on any  $S$  (see later for an approximation).

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# Stationary models

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$$\varphi \leq 1.$$

To construct parametric families of DPP :

Consider parametric families of  $C_0$  and rescale so that  $\varphi \leq 1$ .

→ *This will induce restriction on the parameter space.*

Several parametric families of covariance functions are available, with closed form expressions for their Fourier transform.

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- For  $d = 2$ , the circular covariance function with range  $\alpha$  is given by

$$C_0(x) = \rho \frac{2}{\pi} \left( \arccos(\|x\|/\alpha) - \|x\|/\alpha \sqrt{1 - (\|x\|/\alpha)^2} \right) \mathbf{1}_{\|x\| < \alpha}.$$

DPP( $C_0$ ) exists iff  $\varphi \leq 1 \Leftrightarrow \rho\alpha^2 \leq 4/\pi$ .

$\Rightarrow$  Tradeoff between the intensity  $\rho$  and the range of repulsion  $\alpha$ .

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- Whittle-Matérn (includes Exponential and Gaussian) :

$$C_0(x) = \rho \frac{2^{1-\nu}}{\Gamma(\nu)} \|x/\alpha\|^\nu K_\nu(\|x/\alpha\|), \quad x \in \mathbb{R}^d,$$

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- Generalized Cauchy

$$C_0(x) = \frac{\rho}{(1 + \|x/\alpha\|^2)^{\nu+d/2}}, \quad x \in \mathbb{R}^d.$$

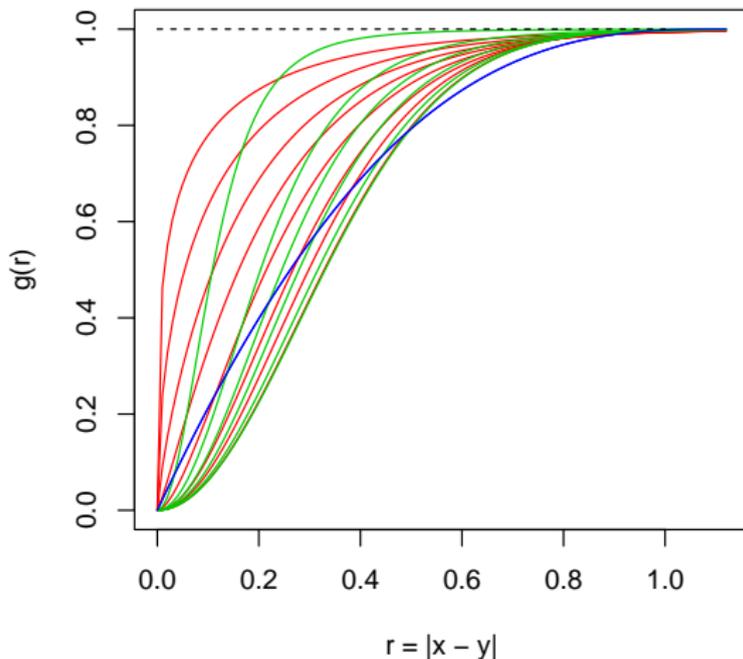
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Pair correlation functions of DPP( $C_0$ ) for previous models when  $\rho = 1$  and  $\alpha = \alpha_{max}(\nu)$ :

In blue :  $C_0$  is the **circular** covariance function.

In red :  $C_0$  is **Whittle-Matérn**, for different values of  $\nu$

In green :  $C_0$  is generalized **Cauchy**, for different values of  $\nu$

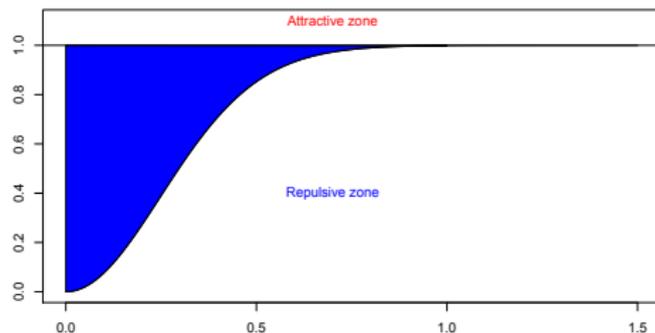


- Are the previous parametric families "rich enough"?
- How repulsive a stationary DPP can be?
  - Less repulsive DPP = Poisson Point Process.
  - What is the most repulsive DPP?
- We introduce criteria of repulsiveness based on the pair correlation function  $g$ .

# How repulsive a stationary DPP can be?

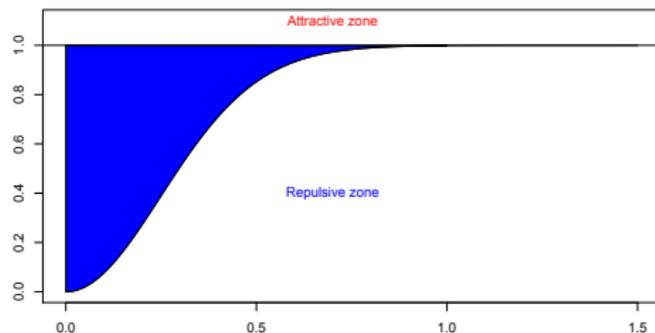
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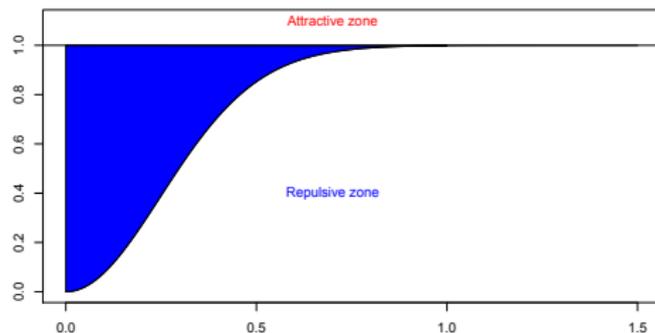
Let  $X$  and  $Y$  be two DPPs with the same intensity  $\rho$  and pcf  $g_X, g_Y$ .

## Definition

- $X$  is *globally more repulsive* than  $Y$  if " $g_X$  has a larger blue zone", i.e.  $\int(1 - g_X) \geq \int(1 - g_Y)$ .

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- $X$  is *locally more repulsive* than  $Y$  if " $g_X$  is more flat near 0", i.e.  $g_X(0) = g_Y(0) = 0$ ,  $\nabla g_X(0) = \nabla g_Y(0) = 0$  and  $\Delta g_X(0) \leq \Delta g_Y(0)$ .

Note that for a hardcore point process:  $g(0) = \nabla g(0) = \Delta g(0) = 0$ .

Let  $J_\nu$  be the Bessel function of the first kind with order  $\nu$ .

### Proposition

*There exists a unique DPP that is both the most globally and the most locally repulsive DPP with intensity  $\rho$ . Its kernel in dimension  $d = 2$  is given by:*

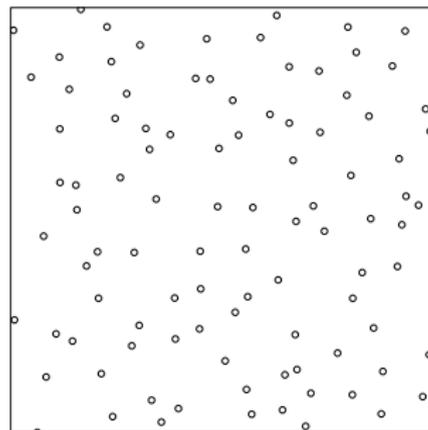
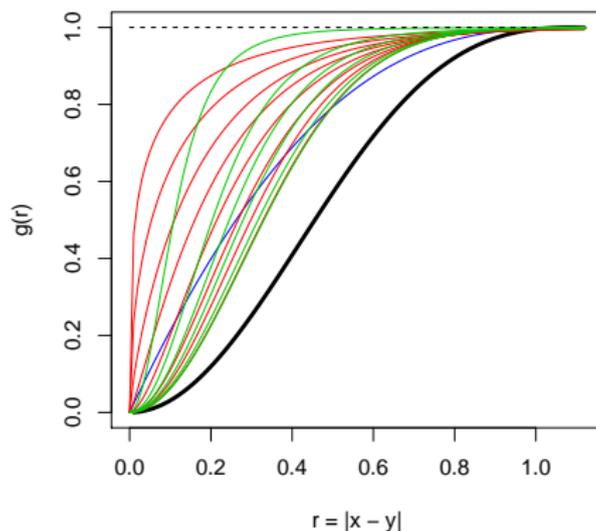
$$C_0(x) = \sqrt{\rho} \frac{J_1(2\sqrt{\pi\rho}\|x\|)}{\sqrt{\pi}\|x\|} \quad \text{and} \quad \varphi(x) = \mathbf{1}_{\|x\|^2 \leq \rho\pi^{-1}}$$

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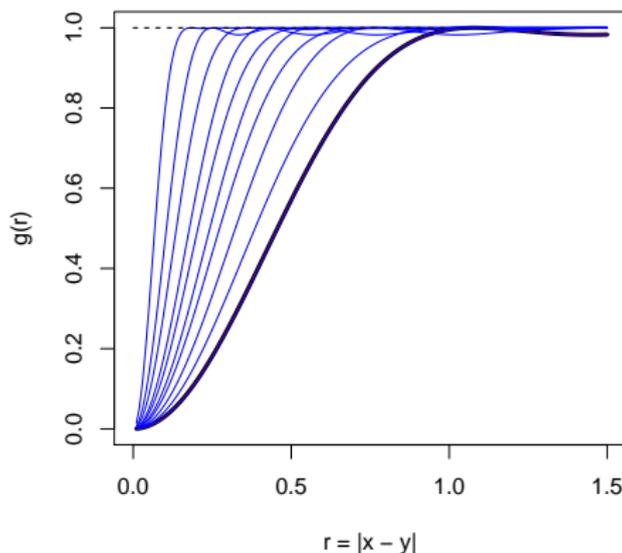
# New parametric families of kernels

# New parametric families of kernels

- Laguerre-Gauss family, for  $n \in \mathbb{N}$  and  $0 < \alpha \leq \alpha_{max}(d, \rho, n)$

$$C_0(x) \propto L_{n-1}^{\frac{d}{2}} \left( \frac{1}{n} \left\| \frac{x}{\alpha} \right\|^2 \right) e^{-\frac{1}{n} \left\| \frac{x}{\alpha} \right\|^2} \quad \varphi(x) \propto e^{-n(\pi\alpha\|x\|)^2} \sum_{k=0}^{n-1} \frac{(\pi\sqrt{n}\|\alpha x\|)^{2k}}{k!}$$

→ covers all possible degrees of repulsiveness.

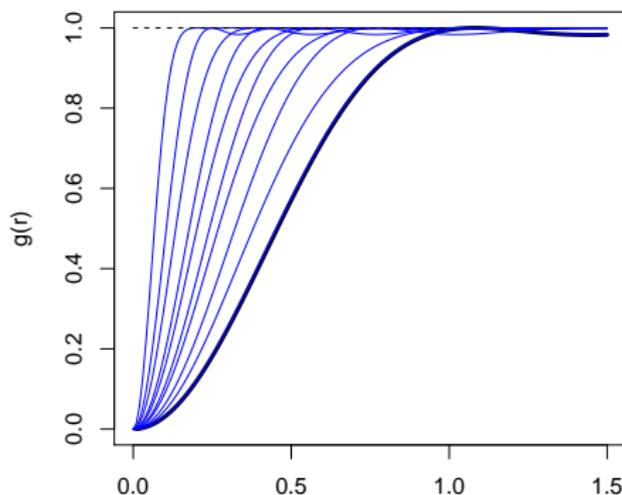


- Generalized-Sinc family, for  $\sigma \geq 0$ ,  $0 < \alpha \leq \alpha_{max}(d, \rho, \sigma)$

$$C_0(x) \propto \frac{J_{\frac{\sigma+d}{2}} \left( 2 \left\| \frac{x}{\alpha} \right\| \sqrt{\frac{\sigma+d}{2}} \right)}{\left( 2 \left\| \frac{x}{\alpha} \right\| \sqrt{\frac{\sigma+d}{2}} \right)^{\frac{\sigma+d}{2}}} \quad \varphi(x) \propto \left( 1 - \frac{2(\pi \|\alpha x\|)^2}{\sigma + d} \right)_+^{\frac{\sigma}{2}}$$

→ covers all possible degrees of repulsiveness.

→  $\varphi$  is compactly supported.



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# Approximation of stationary DPP's models

Consider a stationary kernel  $C_0$  and  $X \sim \text{DPP}(C_0)$ .

- The simulation and the density of  $X_S$  requires the expansion

$$C_S(x, y) = C_0(y - x) = \sum_{k=1}^{\infty} \lambda_k^S \phi_k^S(x) \overline{\phi_k^S(y)}, \quad (x, y) \in S \times S,$$

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- Example: For the circular covariance, this is true whenever  $\rho|S| > 5$ .

# Approximation of stationary models

So,  $\text{DPP}(C_0)$  on  $S$  can be approximated by  $\text{DPP}(C_{\text{app},0})$  with

$$C_{\text{app},0}(y-x) = \sum_{k \in \mathbb{Z}^d} \varphi(k) e^{2\pi i(y-x) \cdot k}, \quad x, y \in S,$$

where  $\varphi$  is the Fourier transform of  $C_0$ .

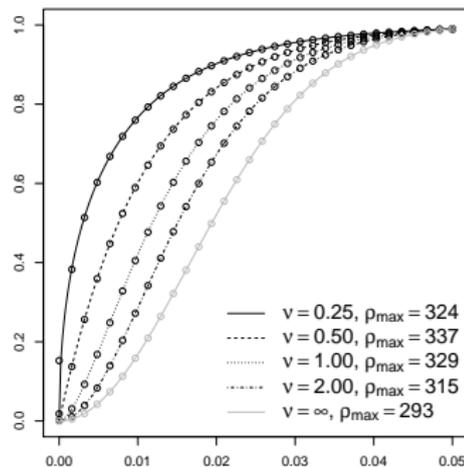
This **kernel approximation** allows us

- to simulate  $\text{DPP}(C_0)$  on  $S$ , by simulating  $\text{DPP}(C_{\text{app},0})$
- to compute the (approximated) density of  $\text{DPP}(C_0)$  on  $S$ .

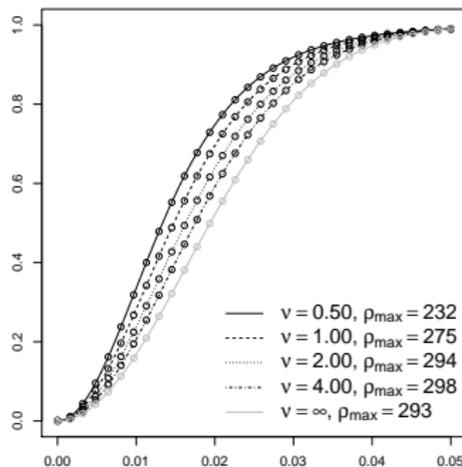
Turns out to be a very good approximation in most cases.

# Exemples of approximations

- Solid lines : theoretical pair correlation function
- Circles : pair correlation from the approximated kernel



Whittle-Matérn



Generalized Cauchy

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Consider a stationary and isotropic parametric DPP( $C_0$ ), with

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where  $R_\theta(0) = 1$  and  $\theta$  is some parameter.

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For this model:

- $\rho =$  intensity.
- Pair correlation function:

$$g(x, y) = 1 - R_\theta(\|x - y\|)^2.$$

# Parameter estimation

In

$$C_0(x - y) = \rho R_\theta(\|x - y\|)$$

we can estimate  $(\rho, \theta)$

- by MLE using the kernel approximation for the likelihood
- or using the moments, for instance :

$$\hat{\rho} = \#\{\text{obs. points}\} / [\text{area of obs. window}]$$

$$\hat{\theta} = \operatorname{argmin}_\theta \int_{r_{\min}}^{r_{\max}} \left| \sqrt{\hat{g}(r)} - \sqrt{g_\theta(r)} \right|^2 dr$$

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# Conclusion

- DPPs provide **flexible** (parametric) models of repulsive point processes and possess **appealing properties**:
  - Easily and rather quickly simulated
  - Closed form expressions for all moments.
  - Closed form expression for the density on any bounded set.
  - Parametric models are available
  - Inference is feasible, including likelihood inference.
  - More: Laplace transform, mixing properties, concentration inequalities, asymptotic inference,...
- Parametric models, inference methods and so on are available in R in the package `spatstat`.

# Conclusion

Some open questions :

- Can we simulate  $\text{DPP}(C)$  without the spectral representation of  $C$ ?
- Theoretical properties for the MLE?
- Theory for inference in the non-homogeneous case
- Semi or non-parametric inference
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*THANK YOU*