# Learning the Structure for Structured Sparsity

Nino Shervashidze joint work with Francis Bach

Journées MAS 31 August 2016





# Introduction

Proposed model

Inference

Regularization

Experiments

Summary and outlook

## Background

**Context**: We are interested in variable selection problems, where a small number of potentially overlapping groups of input variables explains the signal.

#### Examples:

- ► FMRI image classification (e.g., Jenatton *et al.*, 2011a).
- Multiple-loci genome-wide association studies (e.g., Azencott et al., 2013).



Figure by C.-A. Azencott

A standard approach: Regularization with sparsity-inducing norms.

In particular, Jacob *et al.* (2009) and Obozinski and Bach (2012) propose the norm

$$\Omega(w) = \min_{\substack{v_A \in \mathbb{R}^P, \\ \sum_{A \in \mathcal{G}} v_A = w}} \sum_{A \in \mathcal{G}} \|v_A\|_2 f(A)^{1/2},$$

where

- $\mathcal{G} \subseteq 2^{\{1,\dots,P\}}$  is the set of groups,
- P is the number of variables,
- *f*(*A*) represents the prior belief in the subset *A* being relevant: If a group *A* is irrelevant, then *f*(*A*) = +∞.



In particular, Jacob *et al.* (2009) and Obozinski and Bach (2012) propose the norm

$$\Omega(w) = \min_{\substack{v_A \in \mathbb{R}^P, \\ \sum_{A \in \mathcal{G}} v_A = w}} \sum_{A \in \mathcal{G}} \|v_A\|_2 f(A)^{1/2},$$

where

- $\mathcal{G} \subseteq 2^{\{1,\dots,P\}}$  is the set of groups,
- P is the number of variables,
- *f*(*A*) represents the prior belief in the subset *A* being relevant: If a group *A* is irrelevant, then *f*(*A*) = +∞.



**Goal**: Learn the weights f(A), unknown in practice.

Learn the set function  $f : \mathcal{G} \mapsto \mathbb{R}_+ \cup \{+\infty\}$  from data (in other words, learn the structure).

Learn the set function  $f : \mathcal{G} \mapsto \mathbb{R}_+ \cup \{+\infty\}$  from data (in other words, learn the structure).

Remarks:

- 1. This requires a multi-task setting.
- 2. A relevant  $\neq$  A "on" in every single task.

## Introduction

# Proposed model

Inference

Regularization

Experiments

Summary and outlook

Our approach follows the pattern of sparse Bayesian models (Palmer *et al.*, 2006; Seeger and Nickisch, 2011, among others).

Main idea: Place a super-Gaussian sparsity prior on each component of the parameter vector and learn using variational inference.

We take these ideas two steps further:

- we propose a formulation suitable for structured sparsity with any family of groups, as opposed to classical sparsity,
- we learn the hyperparameters that are supposed to be fixed and common to all variables in existing work.

We consider K linear regression problems with

- design matrices  $X^k \in \mathbb{R}^{N^k \times P}$ ,
- response vectors  $y^k \in \mathbb{R}^{N^k}$ ,

 $k \in \{1,\ldots,K\}.$ 

For each  $X^k$  and  $y^k$ , we assume

$$y^k \sim \mathcal{N}(X^k w^k, \sigma^2 I).$$

Example:  $X^k$  – genomes of individuals,  $y^k$  – phenotypes.

Let V be the set  $\{1, \ldots, P\}$ . For  $\mathcal{G} \subseteq 2^V$ , we assume

$$w^k = \sum_{A \in \mathcal{G}} v_A^k$$

where, for each k,

- $\forall A \in \mathcal{G}, v_A^k$  is a vector in  $\mathbb{R}^P$  supported on A,
- $\{v_A^k\}_{A \in \mathcal{G}}$  are jointly independent, and
- $\forall A \in \mathcal{G}, v_A^k$  has a density

$$p(v_A^k|f(A)) = q_A(||v_A^k||_2 f(A)^{1/2}) f(A)^{|A|/2},$$

where  $q_A$  is a zero-mean heavy-tailed distribution.

The inverse scale parameter of the distribution on  $v_A^k$ , f(A), captures the relevance of the group A:

- ► The smaller f(A), the more relevant the group, that is, the larger the values v<sup>k</sup><sub>A</sub> is likely to take.
- ► Even if the group A is relevant, not all v<sup>k</sup><sub>A</sub>, k = 1,..., K have to be large.

Note the resemblance between maximizing log  $p(w^k|f)$  for fixed f

$$\log p(w^k|f) = \sum_{A \in \mathcal{A}} \log q_A(\|v_A^k\|_2 f(A)^{1/2}) + \text{const}$$

and the latent group LASSO norm

$$\Omega(w^k) = \min_{\substack{v_A^k \in \mathbb{R}^P, \\ \sum_{A \in \mathcal{G}} v_A^k = w^k}} \sum_{A \in \mathcal{G}} \|v_A^k\|_2 f(A)^{1/2}.$$

When  $q_A$  is the *generalized Gaussian* density, the two expressions match exactly.

Find  $f(A), A \in \mathcal{G}$ , maximizing the likelihood

$$p(y^1,\ldots,y^K|f) = \prod_{k=1}^K \int p(y^k|X^kw^k,\sigma^2 I) \prod_{A\in\mathcal{G}} p(v_A^k|f(A))dv_A^k,$$

where the  $v_A^k$  are marginalized over.

We assume that  $q_A$  is a scale mixture of Gaussians:

$$q_A(u) = \int_0^\infty \mathcal{N}(u|0,s) r_A(s) ds.$$

Examples: Student's t, generalized Gaussian.

Why?

- 1. Heavy-tailed, hence suitable for modeling sparsity.
- 2. Amenable to variational optimization.

All Gaussian scale mixtures  $q_A$  are also super-Gaussian distributions (Palmer *et al.*, 2006):

- the logarithm of  $q_A$  is convex in  $u^2$ ,
- the logarithm of  $q_A$  is non-increasing.

We can therefore write

$$\operatorname{og} q_A(u) = \sup_{s \ge 0} -\frac{u^2}{2s} - \phi_A(s),$$

where  $\phi(s)$  is convex in 1/s, by convex conjugacy.

Introduction

Proposed model

## Inference

Regularization

Experiments

Summary and outlook

We use variational optimization to infer the set function f from data (building on work by Palmer *et al.* (2006) and Seeger and Nickisch (2011)).

The variational bound on the marginal likelihood p(y|f) is amenable to optimization via alternating analytic updates, finding a local optimum.

The updates are equivalent to mean field updates, using the scale mixture representation of  $q_A$  (Palmer *et al.*, 2006).

#### Does it work?

• K = 10,000, P = 1,  $X^k = 1$  for all  $k \in \{1, ..., K\}$ ,  $\sigma^2 = 1$ .

• 
$$\mathcal{G} = \{\{1\}\}$$
.  $y^k = w^k + \epsilon^k \in \mathbb{R}$ .

- $f \in \{14 \text{ equidistant values on the log. scale in } [0.02, 50]\}.$
- ► Goal: recover f.



Introduction

Proposed model

Inference

Regularization

Experiments

Summary and outlook

Use the improper hyperprior

$$p(f(A)) \propto f(A)^{eta}$$

to encourage f(A) to go to infinity when the variance of  $v_A^k$  is small.

The only update that changes is that for f(A).

### The effect of regularization



Introduction

Proposed model

Inference

Regularization

## Experiments

Summary and outlook

## Signal variance and noise variance

We measure the relevance of the group of variables A by the expectation of  $||v_A^k||_2^2$ ,

$$\mathbb{E}\left[\|\boldsymbol{v}_{A}^{k}\|_{2}^{2}\right] = \frac{\mathbb{E}_{\|\boldsymbol{z}\|_{2} \sim \boldsymbol{q}_{A}}\left[\|\boldsymbol{z}\|_{2}^{2}\right]}{f(A)}$$

As 
$$\mathbb{E}\left[\|w^k\|_2^2\right] = \sum_{A \in \mathcal{A}} \mathbb{E}\left[\|v_A^k\|_2^2\right]$$
,  $\mathbb{E}\left[\|v_A^k\|_2^2\right]$  allows us to measure the contribution of the group  $A$  w.r.t.  $\mathbb{E}\left[\|w^k\|_2^2\right]$ .

We call  $\mathbb{E}\left[\|w^k\|_2^2\right]$  total signal variance,  $\mathbb{E}\left[\|v_A^k\|_2^2\right]$  signal variance coming from the group A, and  $P\sigma^2$  total noise variance.

#### Structured sparsity with two variables

► 
$$K = 5,000, P = 2, X^k = I$$
 for all  $k \in \{1, ..., K\}$ ,  
 $\mathcal{G} = \{\{1\}, \{2\}, \{1, 2\}\}, \sigma^2 = 1.$ 

• Goal: recover  $f(\{1\}), f(\{2\}), f(\{1,2\})$ .



## Structured sparsity with two variables



Red - singletons dominate, blue - pair dominates.

#### Denoising with toy data: Setup

- $K = 10,000, P = 10, X^k = I$  for all  $k \in \{1, \dots, K\}$ .
- ▶  $\mathcal{G} = \{ \{Q\}_{Q=1,...,P}, \{1,...,Q\}_{Q=2,...,P} \}.$
- Goal: Given  $y^k, k \in 1, ..., K$ , find the signals  $w^k$ .



We consider three different ways of generating data:

► Singletons: {1},..., {5} relevant, all other groups irrelevant.



In all cases,  $\sigma^2$  set so that the total signal variance equals the total noise variance.

We consider three different ways of generating data:

- ► Singletons: {1},..., {5} relevant, all other groups irrelevant.
- One group: Only
   {1,2,3,4,5} is relevant.



In all cases,  $\sigma^2$  set so that the total signal variance equals the total noise variance.

We consider three different ways of generating data:

- ► Singletons: {1},..., {5} relevant, all other groups irrelevant.
- One group: Only {1,2,3,4,5} is relevant.
- ► Overlapping groups: The groups {1}, {1,2}, ..., {1,2,3,4,5} are relevant.



In all cases,  $\sigma^2$  set so that the total signal variance equals the total noise variance.







- ► LASSO-like:
  G = {{1},..., {P}}, f(A)
  constant across G.
- ► Weighted LASSO-like:  $\mathcal{G} = \{\{1\}, \dots, \{P\}\}.$
- ► Structured:  $\mathcal{G} = \{\{Q\}_{Q=1,...,P}, \{1,...,Q\}_{Q=2,...,P}\}.$



- ► LASSO-like: *G* = {{1},..., {*P*}}, *f*(*A*) constant across *G*.
- Weighted LASSO-like:  $\mathcal{G} = \{\{1\}, \dots, \{P\}\}.$
- ► Structured:  $G = \{\{Q\}_{Q=1,...,P}, \{1,...,Q\}_{Q=2,...,P}\}.$

# Structured(AS): G not specified in advance.

#### Denoising with toy data: Results



Mean squared error  $\pm$  95%-confidence error bars



- ► Each task is denoising a 32 × 32 image using wavelets (P = 1024).
- ► The Haar wavelet basis for 2-dimensional images (Mallat, 1998) can naturally be arranged in a rooted directed tree.
- We consider four models for inference:
  - ▶ LASSO-like:  $G = \{\{1\}, \ldots, \{P\}\}, f(A) \text{ constant across } G$ .
  - Weighted LASSO-like:  $\mathcal{G} = \{\{1\}, \ldots, \{P\}\}.$
  - Structured:

 $\mathcal{G} = V \cup \{A | A \text{ is a path from the root in the wavelet tree.} \}$ (Jenatton *et al.* (2011b) have shown that structured sparsity-inducing norms with such groups improve over the  $\ell_1$  norm in this task.)

► Structured(AS): *G* not specified in advance.

Goal: Given  $y^k, k \in 1, ..., K$ , find the images  $w^k$ .



	Barbara	House	Fingerprint	Lena
LASSO-like	179.0±4.6 (0.001)	107.5±2.6 (0.001)	247.5±1.7 (0.005)	110.3±2.8 (0.001)
W.LASSO-like	163.3±5.1 (0)	93.7±2.6 (0)	$195.0 \pm 1.8 (0.0001)$	89.5±3.2 (0)
Structured	164.8±5.3 (0)	95.3±2.9 (0)	193.6±1.8 (0.0005)	90.3±3.5 (0)
Structured(AS)	163.1±5.0 (0.0001)	92.9±2.3 (0.0001)	194.9±1.8 (0.001)	89.5±2.8 (0.0001)
Tree-l <sub>2</sub>	155.3±6.4	93.3±3.8	214.9±2.4	88.7±3.7
LASSO	176.7±6.4	102.1±3.6	250.0±2.2	106.6±3.9

Introduction

Proposed model

Inference

Regularization

Experiments

Summary and outlook

# Summary and outlook

- ► We propose a general model and an associated inference scheme to automatically learn group weights for structured sparse linear regression.
- We propose a regularization method that in practice circumvents the problems of the classical variational scheme for our model.
- We propose a heuristic allowing to explore a large set of groups.
- Experimental results in denoising show that learning group weights can make a difference.

# Summary and outlook

- ► We propose a general model and an associated inference scheme to automatically learn group weights for structured sparse linear regression.
- We propose a regularization method that in practice circumvents the problems of the classical variational scheme for our model.
- We propose a heuristic allowing to explore a large set of groups.
- Experimental results in denoising show that learning group weights can make a difference.
- ► Other likelihood models (e.g., for *y*<sup>k</sup> binary)?
- Avoid considering  $v_A^k$  explicitly (for computational efficiency)?
- GWAS application

N. Shervashidze and F. Bach. Learning the structure for structured sparsity. *IEEE Transactions on Signal Processing*, 63(18):4894-4902, 2015.

http://cbio.ensmp.fr/~nshervashidze/code/LLSS

Francis Bach

Guillaume Obozinski Julien Mairal Laurent Jacob Sylvain Arlot

Thank you!

- C.-A. Azencott, D. Grimm, M. Sugiyama, Y. Kawahara, and K. M. Borgwardt. Efficient network-guided multi-locus association mapping with graph cut. *Bioinformatics*, 29(13):i171–i179, 2013.
- L. Jacob, G. Obozinski, and J.-P. Vert. Group Lasso with overlap and graph Lasso. In *Proceedings of the International Conference on Machine Learning*, 2009.
- R. Jenatton, J.-Y. Audibert, and F. Bach. Structured variable selection with sparsity-inducing norms. *Journal of Machine Learning Research*, 12:2777–2824, 2011.
- R. Jenatton, J. Mairal, G. Obozinski, and F. Bach. Proximal methods for hierarchical sparse coding. *Journal of Machine Learning Research*, 12:2297–2334, 2011.
- S. Mallat. *A Wavelet Tour of Signal Processing*. Academic Press, 1998.

- G. Obozinski and F. Bach. Convex relaxation for combinatorial penalties. Technical Report hal-00694765, May 2012.
- J. A. Palmer, D. P. Wipf, K. Kreutz-Delgado, and B. D. Rao. Variational EM algorithms for non-gaussian latent variable models. In Advances in Neural Information Processing Systems, 2006.
- M. Seeger and H. Nickisch. Large scale bayesian inference and experimental design for sparse linear models. *SIAM Journal on Imaging Sciences*, 4(1):166–199, 2011.